

# The Dirty MIMO Multiple-Access Channel

Anatoly Khina, Yuval Kochman, and Uri Erez

**Abstract**—In the scalar dirty multiple-access channel, in addition to Gaussian noise, two additive interference signals are present, each known non-causally to a single transmitter. It was shown by Philosof *et al.* that for strong interferences, an i.i.d. ensemble of codes does not achieve the capacity region. Rather, a structured-codes approach was presented, that was shown to be optimal in the limit of high signal-to-noise ratios, where the sum-capacity is dictated by the minimal (“bottleneck”) channel gain. In this paper, we consider the multiple-input multiple-output (MIMO) variant of this setting. In order to incorporate structured codes in this case, one can utilize matrix decompositions that transform the channel into effective parallel scalar dirty multiple-access channels. This approach however suffers from a “bottleneck” effect for each effective scalar channel and therefore the achievable rates strongly depend on the chosen decomposition. It is shown that a recently proposed decomposition, where the diagonals of the effective channel matrices are equal up to a scaling factor, is optimal at high signal-to-noise ratios, under an equal rank assumption. This approach is then extended to any number of transmitters. Finally, an application to physical-layer network coding for the MIMO two-way relay channel is presented.

**Index Terms**—Multiple-access channel, dirty-paper coding, multiple-input multiple-output channel, matrix decomposition, physical-layer network coding, two-way relay channel.

## I. INTRODUCTION

The dirty-paper channel, first introduced by Costa [1], is given by

$$y = x + s + z, \quad (1)$$

where  $y$  is the channel output,  $x$  is the channel input subject to an average power constraint  $P$ ,  $z$  is an additive white Gaussian noise (AWGN) of unit power, and  $s$  is an interference which is known non-causally to the transmitter but not to the receiver.

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Costa [1] showed that the capacity of this channel, when the interference is i.i.d. and Gaussian, is equal to that of an interference-free channel  $\frac{1}{2} \log(1 + P)$ , i.e., as if  $s \equiv 0$ . This result was subsequently extended to ergodic interference in [2] and to arbitrary interference in [3], where to achieve the latter, a structured lattice-based coding scheme was used.

This model serves as an information-theoretic basis for the study of interference cancellation techniques, and was applied to different network communication scenarios; see, e.g., [4].

Its multiple-input multiple-output (MIMO) variant as well as its extension to MIMO broadcast with private messages can be easily treated either directly or via scalar dirty-paper coding (DPC) and an adequate orthogonal matrix decomposition, the most prominent being the singular-value decomposition (SVD) and the QR decomposition (QRD); see, e.g., [5]–[9].

Philosof *et al.* [10] extended the dirty-paper channel to the case of  $K$  multiple (distributed) transmitters, each transmitter, corresponding to a different user, knowing a different part of the interference:

$$y = \sum_{k=1}^K (x_k + s_k) + z, \quad (2)$$

where  $y$  and  $z$  are as before,  $x_k$  ( $k = 1, \dots, K$ ) is the input of transmitter  $k$  and is subject to an average power constraint  $P_k$ , and  $s_k$  is an *arbitrary* interference sequence which is known non-causally to transmitter  $k$  but not to the other transmitters nor to the receiver.

This scenario is encountered in practice in cases where, for instance, non-cooperative base stations transmit data (over a multiple-access link) to a *common receiver* as well as to separate distinct receivers, which serve as interferences known at the transmitters for the communication to the common receiver. This scenario is described in Fig. 1 for  $K = 2$  receivers.

The capacity region of this scenario, termed the *dirty multiple-access channel* (DMAC) in [10], was shown to be contained (“outer bound”) in the region of all rate tuples  $(R_1, \dots, R_K)$  satisfying

$$\sum_{k=1}^K R_k \leq \frac{1}{2} \log \left( 1 + \min_{k=1, \dots, K} P_k \right), \quad (3)$$

and to contain (“achievable region”) all rate tuples  $(R_1, \dots, R_K)$  satisfying<sup>1</sup>

$$\sum_{k=1}^K R_k \leq \frac{1}{2} \left[ \log \left( \frac{1}{K} + \min_{k=1, \dots, K} P_k \right) \right]^+, \quad (4)$$

<sup>1</sup>In addition to (4), other inner bounds which are tighter in certain cases are derived in [10].

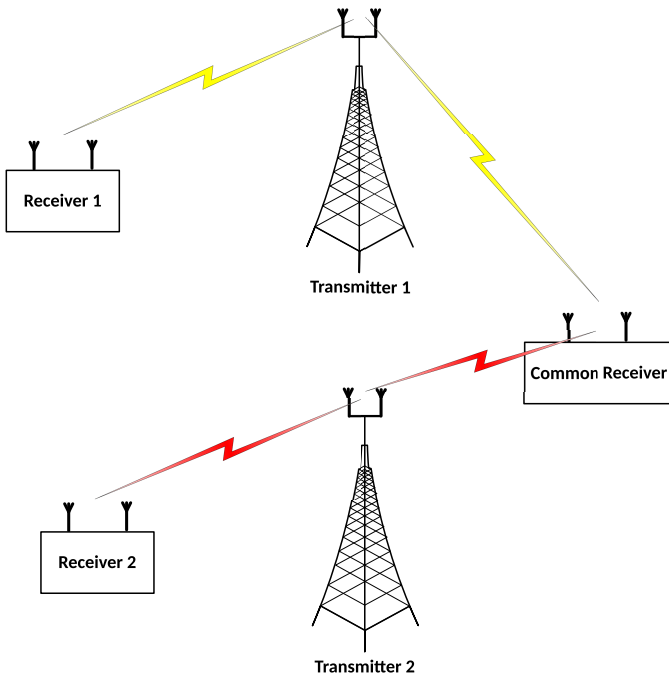


Fig. 1. A wireless dirty-paper channel scenario. The base stations communicate with the *common receiver* over a multiple-access channel as well as with *receiver 1* and *receiver 2* that serve as interferences for the communication to the *common receiver*.

where  $[x]^+ \triangleq \max\{0, x\}$ . These two regions coincide in the limit of high signal-to-noise ratios (SNRs) —  $P_1, \dots, P_K \gg 1$  — thus establishing the capacity region in this limit to be equal to the region of all rate tuples  $(R_1, \dots, R_K)$  satisfying

$$\sum_{k=1}^K R_k \leq \frac{1}{2} \log \left( \min_{k=1, \dots, K} P_k \right). \quad (5)$$

That is, the sum-capacity suffers from a *bottleneck problem* and reduces to the minimum of the individual capacities in this limit, where by the individual capacity of user  $k$ , we mean the capacity from transmitter  $k$  to the receiver where all other transmitters are silent. Interestingly, Costa's random binning technique does not achieve the rate region (4) or the high-SNR region (5), and structured lattice-based techniques need to be used [10], [11].

The MIMO counterpart of the problem is given by

$$\mathbf{y} = \sum_{k=1}^K (\mathbf{H}_k \mathbf{x}_k + \mathbf{s}_k) + \mathbf{z}. \quad (6)$$

For simplicity, we assume for now that all vectors are of equal length  $N$ .<sup>2</sup> We further assume, without loss of generality, that the square channel matrices  $\{\mathbf{H}_k\}$  all have unit determinant, since any other value can be absorbed in  $P_k$ . The AWGN vector  $\mathbf{z}$  has i.i.d. unit-variance elements, while the interference vectors  $\{\mathbf{s}_k\}$  are arbitrary as in the scalar case. The transmitters are subject to average power constraints  $\{P_k\}$ .

<sup>2</sup>We shall depart from this assumption later and treat the more general case of full-rank channel matrices where the number of receive antennas is larger or equal to that of the transmit antennas of each of the transmitters.

In the high-SNR limit (where all powers satisfy  $P_k \gg 1$ ), the individual capacity of the  $k$ -th user is given by:<sup>3</sup>

$$\frac{N}{2} \log \left( \frac{P_k}{N} \right).$$

Thus, similarly to the scalar case (5), one can expect the high-SNR capacity region to be given by

$$\sum_{k=1}^K R_k \leq \frac{N}{2} \log \left( \frac{\min_{k=1, \dots, K} P_k}{N} \right). \quad (7)$$

However, in contrast to the single-user setting (1), the extension of the scalar DMAC to the MIMO case is not straightforward. As structure is required even in the scalar case (2), one cannot use a vector random codebook. To overcome this, we suggest to employ  $N_r$  parallel scalar schemes, each using the lattice coding technique of [10]. This is in the spirit of the capacity-achieving SVD [12] or QRD [13]–[16] based schemes, that were proposed for MIMO communications (motivated by implementation considerations). The total rate is split between multiple scalar codebooks, each one enjoying a channel gain according to the respective diagonal value of the equivalent channel matrix obtained by the channel decomposition.

Unfortunately, for the MIMO DMAC problem, neither the SVD nor the QRD is suitable, i.e., their corresponding achievable rates cannot approach (7). Applying the SVD is not possible in the MIMO DMAC setting as joint diagonalization with the same orthogonal matrix on one side does not exist in general. Applying the QRD to each of the orthogonal matrices, in contrast, is possible as it requires an orthogonal operation only at the transmitter.<sup>4</sup> However, the resulting matrices will have non-equal diagonals in general, corresponding to non-equal SNRs. Specifically, denoting the  $i$ -th diagonal element of the  $k$ -th matrix by  $d_{k;i}$ , the resulting high-SNR sum-rate would be limited to

$$\sum_{k=1}^K R_k \leq \sum_{i=1}^{N_r} \frac{1}{2} \log \left( \frac{\min_{k=1, \dots, K} (P_k d_{k;i}^2)}{N_r} \right) \quad (8)$$

in this case. As this represents a *per-element bottleneck*, the rate is in general much lower than (7).

In this work we make use of a recently proposed joint orthogonal triangularization [17] to remedy the problem, i.e., to transform the per-element bottleneck (8) into a global one as in (7). Specifically, the decomposition allows to transform two matrices (with equal determinants) into triangular ones with *equal diagonals*, using the same orthogonal matrix on the left — corresponding to a common operation carried at the receiver — and different orthogonal matrices on the right — corresponding to different operations applied by each of the transmitters. The equal-diagonals property implies that the minimum in (8) is not active and hence the per-element

<sup>3</sup>The optimal covariance matrix in the limit of high SNR is white; see Lemma 1 in the sequel.

<sup>4</sup>More precisely, RQ decompositions need to be applied to the channel matrices in this case.

bottleneck problem, incurred in the QRD-based scheme, is replaced by the more favorable vector bottleneck (7).

The rest of the paper is organized as follows. We start by introducing the channel model in Section II. We then present the ingredients we use: the matrix decomposition is presented in Section III, and a structured coding scheme for the single-user “dirty” MIMO channel is presented in Section IV. Our main result, the high-SNR capacity of the two-user MIMO DMAC (6) is given in Section V, using a structured scheme. We extend this result to the  $K$ -user case in Section VI. We then demonstrate the usefulness of the proposed technique for MIMO physical-layer network coding in Section VII, by constructing a scheme that achieves capacity in the limit of high SNR for the MIMO two-way relay channel. We conclude the paper in Section VIII.

## II. PROBLEM STATEMENT

The  $K$ -user MIMO DMAC is given by:

$$\mathbf{y} = \sum_{k=1}^K (\mathbf{H}_k \mathbf{x}_k + \mathbf{s}_k) + \mathbf{z}, \quad (9)$$

where  $\mathbf{y}$  is the channel output vector of length  $N_r$ ,<sup>5</sup>  $\mathbf{x}_k$  ( $k = 1, \dots, K$ ) is the input vector of transmitter  $k$  of length  $N_{t;k}$  and is subject to an average power constraint  $P_k$  defined formally in the sequel,  $\mathbf{z}$  is an AWGN vector with an identity covariance matrix, and  $\mathbf{s}_k$  is an interference vector of length  $N_r$  which is known non-causally to transmitter  $k$  but not to the other transmitters nor to the receiver. The interference vector signals  $\{\mathbf{s}_k\}$  are assumed to be arbitrary sequences. We consider a closed-loop scenario, meaning that the  $N_r \times N_{t;k}$  channel matrix  $\mathbf{H}_k$  is known everywhere and that it satisfies the following properties.

**Definition 1** (Proper). A matrix  $\mathbf{H}$  of dimensions  $N_r \times N_t$  is said to be proper if it has no fewer columns than rows, i.e.,  $N_r \leq N_t$ , is full rank (namely of rank  $N_r$ ) and satisfies

$$\det(\mathbf{H}\mathbf{H}^T) = 1. \quad (10)$$

*Remark 1.* Similarly to the special case of full-rank matrices discussed in the introduction, a full-rank  $N_r \times N_t$  matrix  $\mathbf{H}$  with  $N_r \leq N_t$  and  $\det(\mathbf{H}\mathbf{H}^T) = a \neq 1$  may always be normalized to satisfy (10) by absorbing  $a$  in the associated power constraint.

Transmission is carried out in blocks of length  $n$ . The input signal transmitted by transmitter  $k$  is given by

$$\mathbf{x}_k^n = f_k(w_k, \mathbf{s}_k^n),$$

where we denote by  $a^n$  blocks of  $a$  at time instants  $1, 2, \dots, n$ , i.e.,  $a^n = a[1], \dots, a[n]$ ,  $w_k$  is the conveyed message by this user which is chosen uniformly from  $\{1, \dots, \lceil 2^{nR_k} \rceil\}$ ,  $R_k$  is its transmission rate, and  $f_k$  is the encoding function. The input signal  $\mathbf{x}_k$  is subject to an average power constraint

$$\frac{1}{n} \sum_{\ell=1}^n \mathbf{x}_k^2[\ell] \leq P_k.$$

<sup>5</sup>All vectors in this paper are assumed column vectors.

The receiver reconstructs the messages  $\hat{w}_1, \dots, \hat{w}_K$  from the channel output, using a decoding function  $g$ :

$$(\hat{w}_1, \dots, \hat{w}_K) = g(\mathbf{y}^n).$$

A rate tuple  $(R_1, \dots, R_K)$  is said to be achievable if for any  $\epsilon > 0$ , however small, there exist  $n$ ,  $f$  and  $g$ , such that the error probability is bounded from the above by  $\epsilon$ :

$$\Pr(\hat{w}_1 \neq w_1, \dots, \hat{w}_K \neq w_K) \leq \epsilon.$$

The capacity region is defined as the closure of all achievable rate tuples.

## III. BACKGROUND: ORTHOGONAL MATRIX TRIANGULARIZATION

In this section we briefly recall some important matrix decompositions that will be used in the sequel. In Section III-A we recall the generalized triangular decomposition (GTD) and some of its important special cases. Joint orthogonal triangularizations of two matrices are discussed in Section III-B.

### A. Single Matrix Triangularization

Let  $\mathbf{A}$  be a proper matrix (recall Definition 1) of dimensions  $M \times N$ . A generalized triangular decomposition (GTD) of  $\mathbf{A}$  is given by:

$$\mathbf{A} = \mathbf{U}\mathbf{T}\mathbf{V}^T, \quad (11)$$

where  $\mathbf{U}$  and  $\mathbf{V}$  are orthogonal matrices of dimensions  $M \times M$  and  $N \times N$ , respectively, and  $\mathbf{T}$  is a generalized lower-triangular matrix:

$$T_{i,j} = 0, \quad \forall i < j.$$

Namely, it has the following structure:

$$\mathbf{T} = M \left\{ \begin{array}{cccccc} \overbrace{\left[ \begin{array}{cccccc} T_{1,1} & 0 & 0 & \cdots & 0 & \cdots & 0 \\ T_{2,1} & T_{2,2} & 0 & \cdots & 0 & \cdots & 0 \\ \vdots & \vdots & \ddots & & \vdots & \ddots & \vdots \\ T_{M,1} & T_{M,2} & \cdots & T_{M,M} & 0 & \cdots & 0 \end{array} \right]}^N \end{array} \right\}.$$

The diagonal entries of  $\mathbf{T}$  always have a unit product.<sup>6</sup> Necessary and sufficient conditions for the existence of a GTD for a prescribed diagonal  $\{T_{i,i}\}$  are known, along with explicit constructions of such a decomposition [18]–[22].

The following three important special cases of the GTD are well known; all of them are guaranteed to exist for a proper matrix  $\mathbf{A}$ .<sup>7</sup>

1) *SVD* (see, e.g., [24]): Here, the resulting matrix  $\mathbf{T}$  in (11) is a *diagonal* matrix, and its diagonal elements are equal to the singular values of the decomposed matrix  $\mathbf{A}$ .

2) *QR Decomposition* (see, e.g., [24]): In this decomposition, the matrix  $\mathbf{V}$  in (11) equals the identity matrix and hence does not depend on the matrix  $\mathbf{A}$ . This decomposition can be constructed by performing Gram–Schmidt orthonormalization on the (ordered) columns of the matrix  $\mathbf{A}$ .

<sup>6</sup>Since  $\mathbf{A}$  is a proper matrix it is full rank by definition; thus, all the diagonal values of  $\mathbf{T}$ ,  $\{T_{i,i}\}$ , are non-zero.

<sup>7</sup>See [23] for a geometrical interpretation of these decompositions.

3) *GMD* (see [22], [25], [26]): The diagonal elements of  $\mathbf{T}$  in this decomposition are all equal to the geometric mean of its singular values  $\sigma(\mathbf{A})$ , which is real and positive.

### B. Joint Matrix Triangularization

Let  $\mathbf{A}_1$  and  $\mathbf{A}_2$  be two proper matrices of dimensions  $M_1 \times N$  and  $M_2 \times N$ , respectively. A joint triangularization of these two matrices is given by:

$$\mathbf{A}_1 = \mathbf{U}_1 \mathbf{T}_1 \mathbf{V}^T, \quad (12a)$$

$$\mathbf{A}_2 = \mathbf{U}_2 \mathbf{T}_2 \mathbf{V}^T, \quad (12b)$$

where  $\mathbf{U}_1$ ,  $\mathbf{U}_2$  and  $\mathbf{V}$  are orthogonal matrices of dimensions  $M_1 \times M_1$ ,  $M_2 \times M_2$  and  $N \times N$ , respectively, and  $\mathbf{T}_1$  and  $\mathbf{T}_2$  are generalized lower-triangular matrices of dimensions  $M_1 \times N$  and  $M_2 \times N$ , respectively.

It turns out that the existence of such a decomposition depends on the diagonal ratios  $\{T_{1;ii}/T_{2;ii}\}$ . Necessary and sufficient conditions were given in [17]. Specifically, it was shown that there always exists a decomposition with unit ratios, i.e.,

$$T_{1;ii} = T_{2;ii}, \quad i = 1, \dots, N.$$

Such a decomposition is coined the joint equi-diagonal triangularization (JET).<sup>8</sup> Technically, the existence of JET is an extension of the existence of the (single-matrix) GMD.

Unfortunately, JET of more than two matrices is in general not possible [23]. Nonetheless, in Section VI we present a way to overcome this obstacle.

## IV. BACKGROUND: SINGLE-USER MIMO DIRTY-PAPER CHANNEL

In this section we review the (single-user) MIMO dirty-paper channel, corresponding to setting  $K = 1$  in (9):

$$\mathbf{y} = \mathbf{H}\mathbf{x} + \mathbf{s} + \mathbf{z}. \quad (13)$$

We suppress the user index of  $\mathbf{x}$ ,  $\mathbf{s}$ ,  $\mathbf{H}$  and  $N_t$  in this case.

For an i.i.d. Gaussian interference vector, a straightforward extension of Costa's random binning scheme achieves the capacity of this channel,

$$C(\mathbf{H}, P) \triangleq \max_{\mathbf{K}: \text{trace}(\mathbf{K}) \leq P} \frac{1}{2} \log |\mathbf{I}_{N_r} + \mathbf{H}\mathbf{K}\mathbf{H}^T|, \quad (14)$$

which is, as in the scalar case, equal to the interference-free capacity. In the high-SNR limit, we have the following.

**Lemma 1** (See, e.g., [27]). *The capacity of the single-user MIMO dirty-paper channel (13) satisfies*

$$\lim_{P \rightarrow \infty} [C - R_{\text{HSNR}}] = 0,$$

where

$$R_{\text{HSNR}} \triangleq \frac{N_r}{2} \log \frac{P}{N_r}. \quad (15)$$

Furthermore, this rate can be achieved by the input covariance matrix

$$\mathbf{K} = \frac{P}{N_t} \mathbf{I}_{N_t}.$$

<sup>8</sup>See [23] for a geometrical interpretation of the JET.

The Costa-style scheme for the MIMO dirty-paper channel suffers from two major drawbacks. First, it requires vector codebooks of dimension  $N_t$ , which depend on the specific channel  $\mathbf{H}$ . And second, it does not admit an arbitrary interference. Both can be resolved by using the orthogonal matrix decompositions of Section III to reduce the coding task to that of coding for the *scalar* dirty-paper channel (1). For each scalar channel, the interference consists of two parts: a linear combination of the elements of the ‘‘physical interference’’  $\mathbf{s}$  and a linear combination of the off-diagonal elements of the triangular matrix which also serves as ‘‘self interference’’. When using the lattice-based scheme of [3], the capacity (14) is achieved even for an arbitrary interference sequence  $\mathbf{s}$ .

*Scheme* (Single-user zero-forcing MIMO DPC).

#### Offline:

- Apply any orthogonal matrix triangularization (11) to the channel matrix  $\mathbf{H}$ , to obtain the orthogonal matrices  $\mathbf{U}$  and  $\mathbf{V}$ , of dimensions  $N_r$  and  $N_t$ , respectively, and the  $N_r \times N_t$  generalized lower-triangular matrix  $\mathbf{T}$ .
- Denote the vector of the diagonal entries of  $\mathbf{T}$  by  $\mathbf{d} \triangleq \text{diag}(\mathbf{T})$ .
- Construct  $N_r$  good unit-power scalar dirty-paper codes with respect to SNRs  $\{d_i^2 P/N_r\}$ .

**Transmitter:** At each time instant:

- Generates  $\{\tilde{x}_i\}$  in a successive manner from first ( $i = 1$ ) to last ( $i = N_r$ ), where  $\tilde{x}_i$  is the corresponding entry of the codeword of sub-channel  $i$ , the interference over this sub-channel is equal to

$$\sum_{\ell=1}^{i-1} T_{i,\ell} \tilde{x}_\ell + \sum_{\ell=1}^{N_r} V_{i,\ell} s_\ell,$$

and  $T_{i,\ell}$  and  $V_{i,\ell}$  denote the  $(i, \ell)$  entries of  $\mathbf{T}$  and  $\mathbf{V}$ , respectively.

- Forms  $\tilde{\mathbf{x}}$  with its first  $N_r$  entries being  $\{\tilde{x}_i\}$  followed by  $(N_t - N_r)$  zeros.
- Transmits  $\mathbf{x}$  which is formed by multiplying  $\tilde{\mathbf{x}}$  by  $\mathbf{V}$ :

$$\mathbf{x} = \mathbf{V}\tilde{\mathbf{x}}.$$

#### Receiver:

- At each time instant forms  $\tilde{\mathbf{y}} = \mathbf{U}^T \mathbf{y}$ .
- Decodes the codebooks using dirty-paper decoders, where  $\tilde{x}_i$  is decoded from  $\tilde{y}_i$ .

As is well known, the zero-forcing (ZF) DPC scheme approaches capacity for proper channel matrices in the limit of high SNR. This is formally stated as a corollary of Lemma 1.

**Corollary 1.** *For any proper channel matrix  $\mathbf{H}$ , the ZF MIMO DPC scheme achieves  $R_{\text{HSNR}}$  (15). Thus, it approaches the capacity of the MIMO dirty-paper channel (13) in the limit  $P \rightarrow \infty$ .*

*Proof.* The ZF MIMO DPC scheme achieves a rate of

$$\begin{aligned} R_{\text{ZF}} &= \sum_{i=1}^{N_r} \frac{1}{2} \log \left( 1 + \frac{P}{N_r} d_i^2 \right) \\ &\geq \sum_{i=1}^{N_r} \frac{1}{2} \log \left( \frac{P}{N_r} d_i^2 \right) \end{aligned}$$

$$\begin{aligned}
&= N_r \cdot \frac{1}{2} \log \left( \frac{P}{N_r} \right) + \frac{1}{2} \log \left( \prod_{i=1}^{N_r} d_i^2 \right) \\
&= \frac{N_r}{2} \log \left( \frac{P}{N_r} \right),
\end{aligned}$$

where the last equality follows from (10).  $\square$

*Remark 2.* A minimum mean square error (MMSE) variant of the scheme achieves capacity for any SNR and any channel matrix (not necessarily proper); see, e.g., [9]. Unfortunately, extending the MMSE variant of the scheme to the DMAC setting is not straightforward, and therefore we shall concentrate on the ZF variant of the scheme.

## V. TWO-USER MIMO DMAC

In this section we derive outer and inner bounds on the capacity region of the two-user MIMO DMAC (9). We show that the two coincide for proper channel matrices in the limit of high SNRs.

The following is a straightforward adaptation of the outer bound of [10] for the scalar case (3) to the two-user MIMO setting (9). It is formally proved in the Appendix.

**Proposition 1** (Two-user sum-capacity outer bound). *The sum-capacity of the two-user MIMO DMAC (9) is bounded from above by the minimum of the individual capacities:*

$$R_1 + R_2 \leq \frac{1}{2} \log \min_{k=1,2} \max_{\mathbf{K}_k: \text{trace}(\mathbf{K}_k) \leq P_k} \left| \mathbf{I} + \mathbf{H}_k \mathbf{K}_k \mathbf{H}_k^T \right|. \quad (16)$$

We next introduce an inner bound that approaches the upper bound (16) in the limit of high SNRs.

**Theorem 1.** *For the two-user MIMO DMAC (9) with any proper channel matrices  $\mathbf{H}_1$  and  $\mathbf{H}_2$ , the region of all non-negative rate pairs  $(R_1, R_2)$  satisfying*

$$R_1 + R_2 \leq \frac{N_r}{2} \left[ \log \left( \frac{\min\{P_1, P_2\}}{N_r} \right) \right]^+ \quad (17)$$

is achievable.

We give a constructive proof, employing a scheme that uses the JET of Section III-B to translate the two-user MIMO DMAC (9) into parallel SISO DMACs with equal channel gains (corresponding to equal diagonals). As explained in the introduction, this specific choice of decomposition is essential.

*Scheme* (Two-user MIMO DMAC).

### Offline:

- Apply the JET of Section III-B to the channel matrices  $\mathbf{H}_1$  and  $\mathbf{H}_2$ , to obtain the orthogonal matrices  $\mathbf{U}$ ,  $\mathbf{V}_1$ , and  $\mathbf{V}_2$ , of dimensions  $N_r$ ,  $N_{t;1}$  and  $N_{t;2}$ , respectively, and the generalized lower-triangular matrices  $\mathbf{T}_1$  and  $\mathbf{T}_2$  of dimensions  $N_r \times N_{t;1}$  and  $N_r \times N_{t;2}$ , respectively.
- Denote the  $N_r$  diagonal elements of  $\mathbf{T}_1$  and  $\mathbf{T}_2$  by  $\{d_i\}$  (which are equal for both matrices).
- Construct  $N_r$  good unit-power scalar DMAC codes with respect to SNR pairs  $\{(d_i^2 P_1 / N_r, d_i^2 P_2 / N_r)\}$ .

**Transmitter  $k$  ( $k = 1, 2$ ):** At each time instant:

- Generates  $\{\tilde{x}_{k;i}\}$  in a successive manner from first ( $i = 1$ ) to last ( $i = N_r$ ), where  $\tilde{x}_{k;i}$  is the corresponding entry of the codeword of user  $k$  over sub-channel  $i$ , the interference over this sub-channel is equal to

$$\sum_{\ell=1}^{i-1} T_{k;i,\ell} \tilde{x}_{k;\ell} + \sum_{\ell=1}^{N_r} V_{k;i,\ell} s_{k;\ell},$$

$T_{k;i,\ell}$  and  $V_{k;i,\ell}$  are the  $(i, \ell)$  entries of  $\mathbf{T}_k$  and  $\mathbf{V}_K$ , respectively, and  $s_{k;\ell}$  is the  $\ell$ -th entry of  $\mathbf{s}_k$ .

- Forms  $\tilde{\mathbf{x}}_k$  with its first  $N_r$  entries being  $\{\tilde{x}_{k;i}\}$  followed by  $(N_{t;k} - N_r)$  zeros.
- Transmits  $\mathbf{x}_k$  which is formed by multiplying  $\tilde{\mathbf{x}}_k$  by  $\mathbf{V}_k$ :

$$\mathbf{x}_k = \mathbf{V}_k \tilde{\mathbf{x}}_k.$$

### Receiver:

- At each time instant, forms  $\tilde{\mathbf{y}}$  according to:

$$\tilde{\mathbf{y}} = \tilde{\mathbf{U}}^T \mathbf{y}.$$

- Decodes the codebooks using the decoders of the scalar DMAC codes, where  $\tilde{x}_{1,i}$  and  $\tilde{x}_{2,i}$  are decoded from  $\tilde{y}_i$ .

We use this scheme for the proof of the theorem.

*Proof of Theorem 1.* The proposed scheme achieves any rate pair  $(R_1, R_2)$  whose sum-rate is bounded from below by

$$R_1 + R_2 = \sum_{i=1}^{N_r} (r_{1;i} + r_{2;i}) \quad (18a)$$

$$\geq \sum_{i=1}^{N_r} \frac{1}{2} \left[ \log \left( \frac{1}{2} + d_i^2 \cdot \frac{\min\{P_1, P_2\}}{N_r} \right) \right]^+ \quad (18b)$$

$$\geq \sum_{i=1}^{N_r} \frac{1}{2} \log \left( d_i^2 \cdot \frac{\min\{P_1, P_2\}}{N_r} \right) \quad (18c)$$

$$= \sum_{i=1}^{N_r} \frac{1}{2} \log d_i^2 + \sum_{i=1}^{N_r} \frac{1}{2} \log \left( \frac{\min\{P_1, P_2\}}{N_r} \right) \quad (18d)$$

$$= \frac{N_r}{2} \log \left( \frac{\min\{P_1, P_2\}}{N_r} \right), \quad (18e)$$

where  $r_{k;i}$  is the achievable rate of transmitter  $k$  ( $k = 1, 2$ ) over sub-channel  $i$  ( $i = 1, \dots, N_r$ ), (18b) follows from (4), and (18e) holds true due to (10).  $\square$

By comparing Proposition 1 with Theorem 1 in the limit of high SNR, (recall Lemma 1), the following corollary follows.

**Corollary 2.** *The capacity region of the two-user MIMO DMAC (9) with any proper channel matrices  $\mathbf{H}_1$  and  $\mathbf{H}_2$  is given by  $\mathcal{C}_{\text{HSNR}} + o(1)$ , where  $\mathcal{C}_{\text{HSNR}}$  is given by all rate pairs satisfying:*

$$R_1 + R_2 \leq \frac{N_r}{2} \log \left( \frac{\min\{P_1, P_2\}}{N_r} \right)$$

and  $o(1)$  vanishes as  $\min\{P_1, P_2\} \rightarrow \infty$ .

*Remark 3.* At any finite SNR, the scheme can achieve rates outside  $\mathcal{C}_{\text{HSNR}}$ . Specifically, the inequality (18c) is strict, unless the achievable sum-rate is zero. However, in that case the calculation depends upon the exact diagonal values  $\{d_i\}$ ; we do not pursue this direction.

## VI. $K$ -USER MIMO DMAC

In this section we extend the results obtained in Section V to MIMO DMACs with  $K > 2$  users.

The outer bound is a straightforward extension of the two-user case of Proposition 1.

**Proposition 2** ( $K$ -user sum-capacity outer bound). *The sum-capacity of the  $K$ -user MIMO DMAC (9) is bounded from the above by the minimum of the individual capacities:*

$$\sum_{k=1}^K R_k \leq \frac{1}{2} \log \min_{k=1, \dots, K} \max_{\mathbf{K}_k: \text{trace}(\mathbf{K}_k) \leq P_k} |\mathbf{I} + \mathbf{H}_k \mathbf{K}_k \mathbf{H}_k^T|.$$

For an inner bound, we would have liked to use a JET of  $K > 2$  matrices. As such a decomposition does not exist in general, we present a “workaround”, following [23].

We process jointly  $N$  channel uses and consider them as one time-extended channel use. The corresponding time-extended channel is

$$\mathbf{y} = \sum_{k=1}^K (\mathcal{H}_k \mathbf{x}_k + \mathbf{d}_k) + \mathbf{z},$$

where  $\mathbf{y}$ ,  $\mathbf{x}_k$ ,  $\mathbf{d}_k$ ,  $\mathbf{z}$  are the time-extended vectors composed of  $N$  “physical” (concatenated) output, input, interference and noise vectors, respectively. The corresponding time-extended matrix  $\mathcal{H}_k$  is a block-diagonal matrix whose  $N$  blocks are all equal to  $\mathbf{H}_k$ :

$$\mathcal{H}_k = \mathbf{I}_N \otimes \mathbf{H}_k, \quad (19)$$

where  $\otimes$  denotes the Kronecker product operation (see, e.g., [28, Ch. 4]). As the following result shows, for such block-diagonal matrices we can achieve equal diagonals, up to edge effects that can be made arbitrarily small by utilizing a sufficient number of time extensions  $N$ .

**Theorem 2** ( $K$ -JET with edge effects [23]). *Let  $\mathbf{H}_1, \dots, \mathbf{H}_K$  be  $K$  proper matrices of dimensions  $N_r \times N_{t,1}, \dots, N_r \times N_{t,K}$ , respectively, and construct their time-extended matrices with  $N$  blocks,  $\mathcal{H}_1, \dots, \mathcal{H}_K$ , respectively, according to (19). Denote*

$$\tilde{N} = N - N_r^{K-2} + 1. \quad (20)$$

*Then, there exist matrices  $\mathcal{U}, \mathcal{V}_1, \dots, \mathcal{V}_K$  with orthonormal columns of dimensions  $N_r \tilde{N} \times N_r \tilde{N}, N_{t,1} \tilde{N} \times N_r \tilde{N}, \dots, N_{t,K} \tilde{N} \times N_r \tilde{N}$ , respectively, such that*

$$\mathcal{T}_k = \mathcal{U}^T \mathcal{H}_k \mathcal{V}_k, \quad k = 1, \dots, K,$$

*where  $\mathcal{T}_1, \dots, \mathcal{T}_K$  are lower-triangular matrices of dimensions  $N_r \tilde{N} \times N_r \tilde{N}$  with equal diagonals of unit product.*

The value of  $\tilde{N}$  in (20) stems from a matrix truncation operation where we omit rows for which triangularization is not guaranteed; see, e.g., [23, Section VII-B] for an example of the case  $K = 3$ ,  $N_r = N_{t,1} = N_{t,2} = N_{t,3} = 2$  and general  $N$ .

Since the ratio between  $\tilde{N}$  and  $N$  approaches 1 when  $N$  goes to infinity:

$$\lim_{N \rightarrow \infty} \frac{\tilde{N}}{N} = 1, \quad (21)$$

the loss in rate due to the disparity between them goes to zero. This is stated formally in the following theorem.

**Theorem 3.** *For the  $K$ -user MIMO DMAC (9), the region of all non-negative rate tuples  $(R_1, \dots, R_K)$  satisfying*

$$\sum_{k=1}^K R_k \leq \frac{N_r}{2} \left[ \log \left( \frac{\min_k P_k}{N_r} \right) \right]^+$$

*is achievable.*

*Proof.* Fix some large enough  $N$ . Construct the channel matrices  $\mathcal{H}_1, \dots, \mathcal{H}_K$  as in (19), and set  $\mathcal{U}, \mathcal{V}_1, \dots, \mathcal{V}_K$  and  $\mathcal{T}_1, \dots, \mathcal{T}_K$  according to Theorem 2. Now, over  $n\tilde{N}$  consecutive channel uses, apply the natural extension of the scheme of Section V to  $K$  users, replacing  $\{U_k\}, V, \{T_k\}$  with the obtained matrices. As in the proof of Theorem 1, we can attain any rate approaching

$$\sum_{k=1}^K R_k \leq \frac{N_r \tilde{N}}{2} \log \frac{\min_{k=1, \dots, K} P_k}{N_r}.$$

As we used the channel  $n\tilde{N}$  times, we need to divide these rates by  $\tilde{N}$ ; by (21) the proof is complete.  $\square$

By comparing Proposition 2 with Theorem 3 in the limit of high SNR, we can extend Corollary 2 as follows.

**Corollary 3.** *The capacity region of the  $K$ -user MIMO DMAC (9) with any proper channel matrices  $\mathbf{H}_1, \dots, \mathbf{H}_K$  is given by  $\mathcal{C}_{\text{HSNR}} + o(1)$ , where  $\mathcal{C}_{\text{HSNR}}$  is given by all rate pairs satisfying:*

$$\sum_{k=1}^K R_k \leq \frac{N_r}{2} \log \left( \frac{\min_{k=1, \dots, K} P_k}{N_r} \right)$$

*and  $o(1)$  vanishes as  $\min_{k=1, \dots, K} P_k \rightarrow \infty$ .*

**Remark 4.** To approach the rate of Theorem 3 for  $K > 2$  users, the number of time extensions  $N$  needs to be taken to infinity, in general. Using a finite number of time extensions entails a loss in performance, which decays when this number is increased. On the other hand, a large number of time extensions requires using a longer block, or alternatively, if the blocklength is limited, this corresponds to shortening the effective blocklength of the scalar codes used, which in turn translates to a loss in performance. Hence in practice, striking a balance between these two losses is required, by selecting an appropriate number of time extensions  $N$ . For further discussion and details, see [23].

## VII. APPLICATION TO THE MIMO TWO-WAY RELAY CHANNEL

In this section we apply the MIMO DMAC scheme of Section V to the MIMO two-way relay channel (TWRC). For Gaussian scalar channels, the similarity between these two settings was previously observed; see, e.g., [4].

As in the scalar DMAC setting (2), structured schemes based on lattice coding are known to be optimal in the limit of high SNR for the scalar TWRC [29], [30]. This suggests

in turn that, like in the MIMO DMAC setting, using the JET in conjunction with scalar lattice codes can achieve a similar result in the MIMO TWRC setting.

We start by introducing the MIMO TWRC model.

### A. Channel Model

The TWRC consists of two terminals and a relay. We define the channel model as follows. Transmission takes place in two phases, each one, without loss of generality, consisting of  $n$  channel uses. At each time instant  $i$  in the first phase, terminal  $k$  ( $k = 1, 2$ ) transmits a signal  $x_{k;i}$  and the relay receives  $y_i$  according to some memoryless multiple-access channel (MAC)  $W_{\text{MAC}}(y|x_1, x_2)$ . At each time instant  $i$  in the second phase, the relay transmits a signal  $x_i$  and terminal  $k$  ( $k = 1, 2$ ) receives  $y_{k;i}$  according to some memoryless broadcast (BC) channel  $W_{\text{BC}}(y_1, y_2|x)$ . Before transmission begins, terminal  $k$  possesses an independent message of rate  $R_k$ , unknown to the other nodes; at the end of the two transmission phases, each terminal should be able to decode, with arbitrarily low error probability, the message of the other terminal. The closure of all achievable rate pairs  $(R_1, R_2)$  is the capacity region of the network.

In the Gaussian MIMO setting, terminal  $k$  ( $k = 1, 2$ ) has  $N_{t;k}$  transmit antennas and the relay has  $N_r$  receive antennas, during the MAC phase (see also Fig. 2a):

$$\mathbf{y} = \mathbf{H}_1 \mathbf{x}_1 + \mathbf{H}_2 \mathbf{x}_2 + \mathbf{z},$$

where the channel matrices  $\mathbf{H}_k$  and the vectors  $\mathbf{z}$  are defined as in (9). We assume that the channel matrices are proper.<sup>9</sup> We denote by  $\mathbf{K}_k$  ( $k = 1, 2$ ) the input covariance matrix used by terminal  $k$  during transmission.

We shall concentrate on the symmetric setting:

$$\begin{aligned} R_1 &= R_2 \triangleq R, \\ P_1 &= P_2 \triangleq P. \end{aligned}$$

The exact nature of the BC channel is not material in the context of this work. We characterize it by its common-message capacity  $C_{\text{common}}$ .

Before treating the MIMO setting, we start by reviewing the structured physical network coding (PNC) approach for the scalar setting, in which  $\mathbf{H}_1$  and  $\mathbf{H}_2$  are replaced with scalar channel gains  $h_1$  and  $h_2$ .

### B. PNC for the Scalar Gaussian TWRC

In the scalar case, (10) reduces to

$$h_1 = h_2 = 1.$$

In this case, the min-cut max-flow theorem [32], [33] reduces to the minimum between the individual capacities over the MAC link and the common-message capacity of the BC link (see, e.g., [30, Section III], [34, Section II-A]):

$$R_{\text{CS}} = \min \left\{ \frac{1}{2} \log(1 + P), C_{\text{common}} \right\}. \quad (23)$$

<sup>9</sup>For a treatment of the case of non-proper channel matrices, see [31].

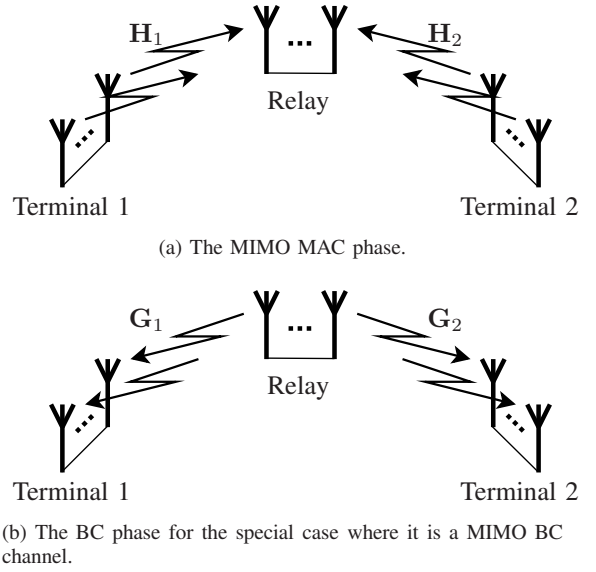


Fig. 2. The MIMO two-way relay channel. The second (BC) phase may be different in general.

In the (structured) PNC approach [29], both terminals transmit codewords generated from the same lattice code. Due to the linearity property of the lattice code, the sum of the two codewords is a valid lattice codeword. This sum is decoded at the relay and sent to the terminals. Each terminal then recovers the sum codeword and subtracts from it its own lattice codeword, to obtain the codeword transmitted by the other terminal. The rate achievable using this scheme is given by [29], [30]:

$$R_{\text{PNC}} = \min \left\{ \left[ \frac{1}{2} \log \left( \frac{1}{2} + P \right) \right]^+, C_{\text{common}} \right\}. \quad (24)$$

As is shown in [30], the PNC rate (24) is within half a bit from the cut-set bound (23) and approaches the cut-set bound in the limit of high SNR. We next extend the asymptotic optimality of the PNC scheme to the MIMO setting.

We note that, in the scalar case, other strategies can also be used rather than PNC, yielding better performance at different parameter regimes. We address these strategies in Section VII-D along with their extension to the MIMO setting.

### C. PNC for the Gaussian MIMO TWRC

The cut-set bound, in this case, is given by

$$R_{\text{CS}} = \min \{C_1, C_2, C_{\text{common}}\},$$

where

$$C_k \triangleq \max_{\mathbf{K}_k} \frac{1}{2} \log |\mathbf{I} + \mathbf{H}_k \mathbf{K}_k \mathbf{H}_k^T|, \quad k = 1, 2,$$

are the individual capacities of the MIMO links, and the maximization is carried over all  $\mathbf{K}_k$  subject to the input power constraint  $P$ .

The PNC approach can be extended to work for the MIMO case by applying the JET of Section III-A to the channel matrices  $\mathbf{H}_1$  and  $\mathbf{H}_2$ . The off-diagonal elements of the resulting

triangular matrices are treated as interferences known at the transmitters. Specifically, the following rate is achievable:<sup>10</sup>

$$R = \min \left\{ \frac{N_r}{2} \log \left( \frac{P}{N_r} \right), C_{\text{common}} \right\}. \quad (25)$$

To see this, use the scheme for MIMO DMAC of Section V with the DMAC codes replaced with PNC ones: over each sub-channel, each of the users transmits a codeword from the (same) lattice, and the relay (who takes the role of the receiver in the scheme for the MIMO DMAC) recovers the sum codeword (modulo the coarse lattice) as in scalar PNC and continues as in the standard scalar PNC scheme. The achievable symmetric-rate is equal to the sum-rate achievable by the MIMO DMAC scheme (17), which is equal, in turn, to (25).

The achievability of (25) implies that when the channel is “MAC-limited” (the bottleneck being the first phase), the capacity in the high SNR regime is achieved by applying the JET to the channel matrices and using PNC over the resulting scalar channels.

*Remark 5* (MIMO BC phase). The only assumption we used regarding the BC section is that it has a common-message capacity  $C_{\text{common}}$ . However, it seems likely that the links to the terminal will be wireless MIMO ones as well. In that case, depicted also in Fig. 2b, the complexity may be considerably reduced by using a scheme that is based upon the JET, for that section as well; see [17].

#### D. Extensions and Comparisons

A different approach to the MIMO TWRC was proposed by Yang *et al.* [35]. In this approach, parallel scalar TWRCs are obtained via a joint matrix decomposition, but instead of the JET, the generalized singular value decomposition (GSVD) [24], [36] is used, which may be seen as a different choice of joint matrix triangularization (12); also, rather than DPC, successive interference cancellation (SIC) is used.

We next compare the approaches, followed by a numerical example; the reader is referred to [34] for further details.

- 1) **High-SNR optimality.** In the symmetric case (22), both approaches achieve the high-SNR optimal rate (25).
- 2) **Finite-SNR improvements.** At finite SNR, one can easily improve upon (25) to get a slightly better rate, see Remark 3. As we show in [34, Thm. 1] using the technique of [37], the finite-SNR rate of the GSVD-based scheme can also be slightly improved.<sup>11</sup> Analytically comparing the finite-SNR performance of the schemes after the improvement is difficult, although numerical evidence suggests that the JET-based scheme has better finite-SNR performance in many cases (e.g., Example 1).
- 3) **Use of any strategy.** For the scalar case, we note the following approaches, as an alternative to physical PNC. In the decode-and-forward (DF) approach, the relay

decodes both messages with sum-rate  $2R$ . Instead of forwarding both messages, it can use a network-coding approach [39] and sum them bitwise modulo-2 (“XOR them”). Then, each terminal can XOR out its own message to obtain the desired one. In the compress-and-forward (CF) approach, the noisy sum of the signals transmitted by the sources is quantized at the relay, using remote Wyner–Ziv coding [40], with each terminal using its transmitted signal as decoder side-information. The CF and DF strategies both have an advantage over physical PNC for some parameters. Further, [41] presents various layered combinations of the CF and DF approaches, which yield some improvement over the two. Constructing an optimized scheme via time-sharing between these approaches is pursued in [34].

Turning our attention to the MIMO setting, since the JET approach uses DPC, any strategy can be used over the subchannels; the decoder for each subchannel will receive an input signal as if this were the only channel. In contrast, the GSVD approach uses SIC, where the task of canceling inter-channel interference is left to the relay. In order to cancel out interference, the relay thus needs to decode; this prohibits the use of CF.

- 4) **Asymmetric case.** The GSVD-based approach is suitable for any ratio of rates and powers between the users, and in fact it is optimal in the high-SNR limit for any such ratio. Since the JET-based PNC scheme uses the MIMO DMAC scheme of Section V for transmission during the MAC phase, it is limited by the minimum of the powers of the two terminals and cannot leverage excess power in case the transmit powers are different.<sup>12</sup> To take advantage of the excess power in case of unequal transmit powers for this scheme, one can superimpose a DF strategy for the stronger user on top of the symmetric JET-based PNC scheme, as was proposed in [43].

*Example 1.* Consider a Gaussian MIMO TWRC with a MAC phase comprising two parallel asymmetric channels

$$\mathbf{H}_1 = \begin{pmatrix} 1/4 & 0 \\ 0 & 4 \end{pmatrix}, \quad \mathbf{H}_2 = \begin{pmatrix} 4 & 0 \\ 0 & 1/4 \end{pmatrix},$$

and a common-message BC capacity of  $C_{\text{common}} = 20$  bits, where the terminals are subject to a per-antenna individual power constraint  $P$ .

Fig. 3 depicts the different achievable rates mentioned in this section as a function of  $P$ . In contrast to the case of general channel matrices, in the case of parallel channels (corresponding to diagonal channel matrices), all the scalar asymmetric techniques can be used. Nonetheless, when considering high enough SNR, where PNC is advantageous, one observes that such asymmetric techniques are inferior to their symmetric counterparts (resulting after applying the JET). This gap is especially pronounced, if we compare the optimum asymmetric strategy with the optimal JET-based hybrid strategy.

<sup>10</sup>Indeed, the same was proven using a different approach [35], see Section VII-D in the sequel for a comparison.

<sup>11</sup>[38] also introduces an improvement to the GSVD-based scheme for certain special cases, but it is subsumed by the improvement in [34].

<sup>12</sup>This statement is precise when the SNRs are high and the interferences are strong. Otherwise, some improvements are possible [10], [42].



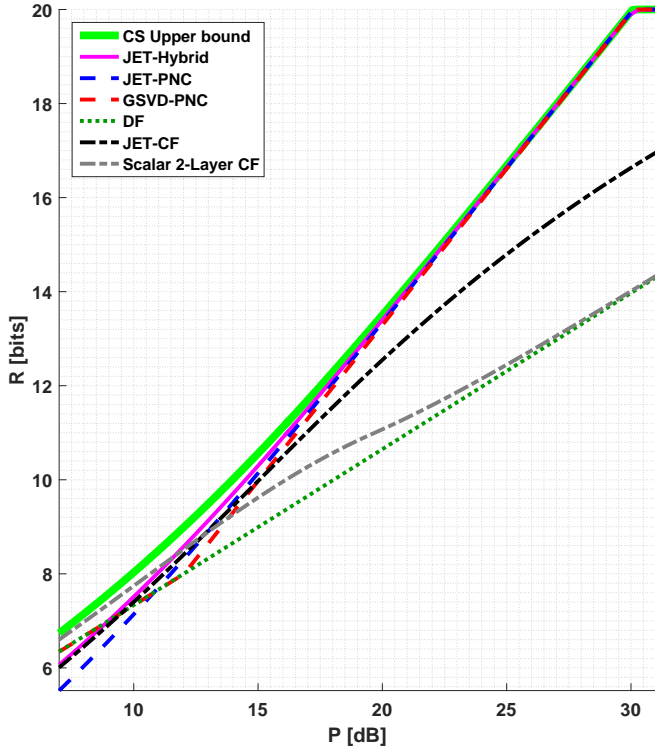


Fig. 3. Performance of the proposed strategies for  $\mathbf{H}_1 = \text{diag}(1/4, 4)$ ,  $\mathbf{H}_2 = \text{diag}(4, 1/4)$  and  $C_{\text{common}} = 20\text{bits}$ .

### VIII. DISCUSSION: GENERAL CHANNEL MATRICES

In this paper we restricted attention to full rank channel matrices having more columns than rows. In this case, the column spaces of both matrices are equal. Indeed, the scheme and inner bound of Sections V and VI can be extended to work for the general case as well; this requires, however, introducing an output projection at the receiver, which transforms the channel matrices to effective proper ones. Since all interferences need to be canceled out for the recovery of the transmitted messages, it seems that such a scheme would be optimal in the limit of large transmit powers  $P_1, \dots, P_K \rightarrow \infty$ . Unfortunately, the upper bound of Proposition 1, which is equal to the maximal individual capacity, is not tight in the non-proper matrix case, which calls for further research.

#### APPENDIX PROOF OF COROLLARY 2

The proof of Corollary 2 is a simple adaptation of the proof of the outer bound for the scalar case (3) of [10].

Take  $s_2 \equiv 0$  and  $s_1$  to be i.i.d. Gaussian with zero mean and scaled-identity covariance matrix  $Q_1 \mathbf{I}_{N_r}$ . Further assume that both users wish to transmit the same common message  $w$ , and denote the rate of this message by  $R$ . Clearly, the supremum over all achievable rates  $R$  bounds from the above the sum-capacity of the two-user MIMO DMAC.

By applying Fano's inequality, we have

$$nR \leq H(w) \quad (26a)$$

$$= H(w|\mathbf{y}^n) + I(w; \mathbf{y}^n) \quad (26b)$$

$$= I(w; \mathbf{y}^n) + n\epsilon_n, \quad (26c)$$

where  $\epsilon_n \rightarrow 0$  as the error probability goes to zero and  $n \rightarrow \infty$ . By retracing (120)–(125) of [10] we attain

$$I(w; \mathbf{y}^n) \leq h(\mathbf{y}^n) - h(\mathbf{z}^n) - h(s_1^n) + h(\mathbf{H}_1 \mathbf{x}_1^n + \mathbf{z}^n). \quad (27)$$

By recalling that  $s_1 \sim \mathcal{N}(\mathbf{0}, \mathbf{I}_{N_r})$  and using the Cauchy–Schwarz inequality, we have

$$h(\mathbf{H}_1 \mathbf{x}_1^n + \mathbf{z}^n) \leq \frac{n}{2} \log |\mathbf{I}_{N_r} + \mathbf{H}_1 \mathbf{K}_1 \mathbf{H}_1^T|, \quad (28a)$$

$$h(\mathbf{y}^n) \leq \frac{nN_r}{2} \log(Q_1) \cdot (1 + o(1)), \quad (28b)$$

where  $o(1) \rightarrow 0$  for  $Q_1 \rightarrow \infty$ .

By substituting (28) in (27) and the outcome in (26c), and taking  $Q_1 \rightarrow \infty$ , we attain

$$R \leq \frac{1}{2} \log |\mathbf{I}_{N_r} + \mathbf{H}_1 \mathbf{K}_1 \mathbf{H}_1^T| + \epsilon_n.$$

By switching roles between the users, the following upper bound holds

$$R \leq \frac{1}{2} \log |\mathbf{I}_{N_r} + \mathbf{H}_2 \mathbf{K}_2 \mathbf{H}_2^T| + \epsilon_n,$$

and the desired result follows.  $\blacksquare$

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